Modbus Reading for Schneider PowerLogic PM8000

This is a specification and implementation of the Arduino-based Modbus data logger for the Schneider PowerLogic PM8000. This software is designed for Vivarox EMS and only Vivarox has right to use and modify this software.

Arduino Implementation:

This project uses an Arduino MEGA 2560 to connect to Modbus devices, read information, and log it onto an SD card with timestamps. The MEGA 2560 is particularly well-suited for this project due to its increased memory capacity and multiple hardware serial ports.

Hardware needed:

- 1. Arduino Board Required: Arduino MEGA 2560 (selected for its 256KB flash memory, 8KB SRAM, and multiple hardware serial ports)
 - Arduino MEGA @ R377.20
- 2. RS485 to TTL Module Allows communication between the Arduino and Modbus devices using the RS485 protocol.
 - <u>RS485 Module (TTL -> RS485)</u> @ <u>R25.30</u>
 - MAX485 Bus Transceiver (4 Pack) @ R16.00
- 3. SD Card Module Allows the Arduino to read from and write data to an SD card.
 - Micro SD Card Module @ R25.00
- 4. RTC Module To keep track of the current date and time, even when the Arduino is powered off.
 - DS3231 Real Time Clock Module @ R55.20
- 5. Power Supply To power the Arduino and connected peripherals.
 - AC Adapter 9V with barrel jack @ R60
- 6. LED Indicators Two LEDs for status indication (not included in original cost estimate).

Wiring for MEGA 2560

RS485 Module to Arduino MEGA:

- 1. RO (Receiver Output) to MEGA RX1 (pin 19) Using Hardware Serial1
- 2. DI (Driver Input) to MEGA TX1 (pin 18) Using Hardware Serial1
- 3. DE (Driver Enable) & RE (Receiver Enable) to MEGA digital pin 4
- 4. VCC to 5V on MEGA
- 5. GND to GND on MEGA
- 6. A & B (RS485 differential pair) to Modbus device

SD Card Module to Arduino MEGA:

- 1. VCC to 5V on MEGA
- 2. GND to GND on MEGA
- 3. MOSI to MOSI (pin 51)
- 4. MISO to MISO (pin 50)
- 5. SCK to SCK (pin 52)
- 6. CS (Chip Select) to digital pin 53

RTC Module to Arduino MEGA:

- 1. VCC to 5V on the MEGA
- 2. GND to GND on the MEGA
- 3. SDA to SDA (pin 20)
- 4. SCL to SCL (pin 21)

LED Indicators:

- 1. LED A to digital pin 3
- 2. LED B to digital pin 5

Software

- Modbus Library: ModbusMaster
- SD Library: SdFat (more advanced than the standard SD library)
- RTC Library: RTClib by Adafruit

Implementation Details

- 1. Modbus Configuration:
 - Slave ID: 1
 - Baud Rate: 9600
 - Register map: Defined in separate "register map.h" file
 - Using Hardware Serial1 for improved reliability
- 2. Data Logging:
 - Frequency: Readings taken every second
 - File Format: CSV (Comma-Separated Values)
 - Filename: "log_YYYYMMDD.csv" (generated daily based on current date)
 - Data Structure: Timestamp, followed by register values
 - Header Row: Includes register addresses for easy identification
 - Larger buffer sizes possible due to MEGA's increased memory
- 3. Register Types Supported:
 - Float (32-bit)
 - Integer (32-bit)
 - Long (64-bit)
 - String (up to 20 characters)
 - Multiple register reads supported simultaneously due to larger memory
- 4. Error Handling and Status Indication:
 - LED A: Indicates successful data writing and transmission
 - LED B: Indicates errors (e.g., SD card issues, RTC problems, Modbus communication errors)
 - Serial output for debugging (115200 baud possible due to hardware serial)
- 5. Special Features:
 - Automatic creation of new log file on date change
 - Header row written only once per file
 - Robust error handling for SD card, RTC, and Modbus communication
 - Support for larger register maps due to increased memory
 - Possibility to implement multiple Modbus device communication using additional hardware serial ports

Programming Workflow

- 1. Initialize hardware (RTC, SD card, RS485 module)
- 2. Set up Modbus communication parameters using Hardware Serial1
- 3. Enter main loop:
 - Read current time from RTC
 - Read data from Modbus registers (larger batches possible)
 - $\circ\,$ Write timestamped data to SD card
 - $\circ\,$ Handle any errors and provide status indication via LEDs
 - $\circ\,$ Delay for 1 second before next reading

MEGA-Specific Advantages

- More memory allows reading more registers simultaneously
- Hardware serial ports provide more reliable communication
- Additional I/O pins available for expansion
- · Possibility to monitor multiple Modbus devices using different serial ports
- Larger program space allows for more complex error handling and data processing

- No need to be selective about registers due to memory constraints
- Can implement additional features like local display or network connectivity

Best Practices

- Use Hardware Serial1 (pins $^{18}/_{19}$) for primary Modbus communication
- Additional Modbus devices can use Serial2 (pins 16/17) or Serial3 (pins 14/15)
- Take advantage of the extra memory to implement robust error checking
- Consider using the additional I/O pins for status displays or control interfaces
- You can include all registers from your register map without memory concerns
- Consider implementing a circular buffer for temporary data storage